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Abstract. In this work, an event-based optimal state estimation problem for linear-time varying systems with unknown inputs is investigated. By treating the unknown input as a process with a non-informative prior, the event-based minimum mean square error (MMSE) estimator is obtained in a recursive form.

**Event-based state estimation of linear dynamic systems—**

SYSTEM STATE ESTIMATE -III A PRIORI INFORMATION MEASUREMENT ERROR SOURCES SYSTEM ERROR OPTIMAL ESTIMATION An optimal estimator is a computational algorithm that processes measure ments to deduce a minimum error| estimate of the state of a system by utilizing: knowledge ofsystem and measurement dynamics, assumed statistics of

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Optimal Estimation of Dynamic Systems create 1001 synthetic measurements of b and y<sup>~</sup> at 5-second intervals. The estimated output is computed from y<sup>^</sup> = 2bTj c<sup>^</sup> - c<sup>^</sup> T c<sup>^</sup> where c<sup>^</sup> is the estimated solution from the nonlinear least square iterations. Use nonlinear least squares to determine c<sup>^</sup> for a starting value of T xc = 0 0 0 .

**Optimal Estimation of Dynamic Systems, Second Edition—**

An optimal estimator for continuous nonlinear systems with nonlinear dynamics, and nonlinear measurement based on the continuous least square error criterion is derived. The solution is exact, explicit, in closed form and gives recursive formulas of the optimal filter.

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